# Architectures for Distributed Systems

Chapter 2

### Definitions

Software Architectures



### Definitions

#### Software Architectures

- describe the <u>organization</u> and <u>interaction</u> of software components
- focuses on logical organization of software (component interaction, etc.)

### Definitions

#### • System Architectures

- describe the placement of software components on physical machines
- <u>Centralized</u> most components located on a single machine
- <u>Decentralized</u> most machines have approximately the same functionality
- <u>Hybrid</u> some combination.

### Architectural Styles (Software Architectures)

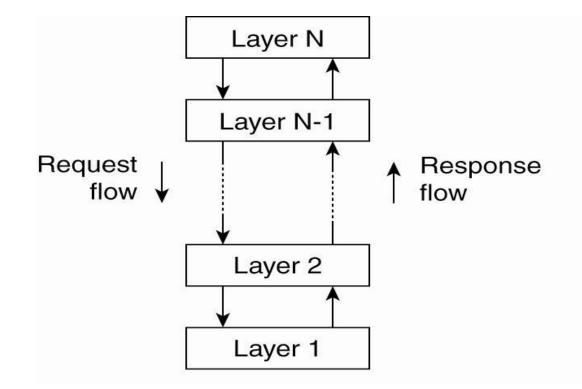
- An **architectural style** describes a particular way to configure a collection of components and connectors.
  - **Component** a module with well-defined interfaces; reusable, replaceable
  - **Connector** communication link between modules

### Architectural Styles

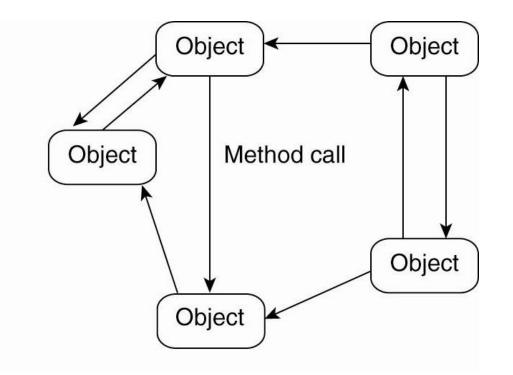
• Architectures suitable for distributed systems:

- Layered architectures
- Object-based architectures
- Data-centered architectures
- Event-based architectures

### Layered architectures



### Object based



Object based is less structured component = object connector = RPC or RMI

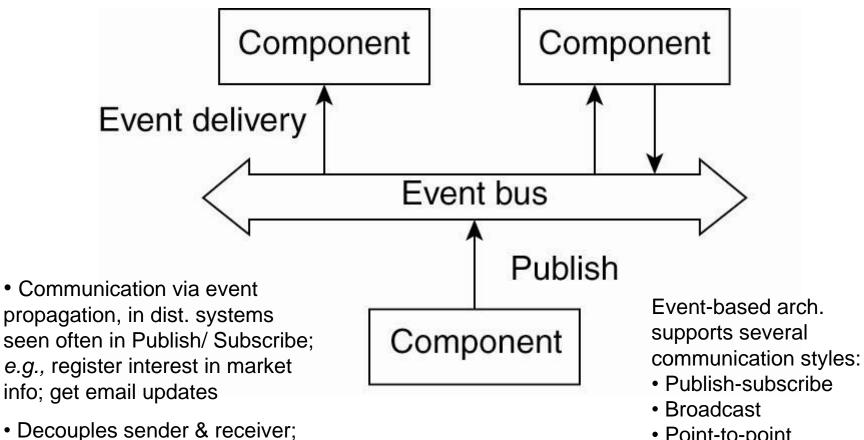
#### **Data-Centered Architectures**

• Main purpose: **data** access and update

• Processes interact by reading and modifying data in some shared repository (active or passive)

• Example: web-based distributed systems where communication is through web services

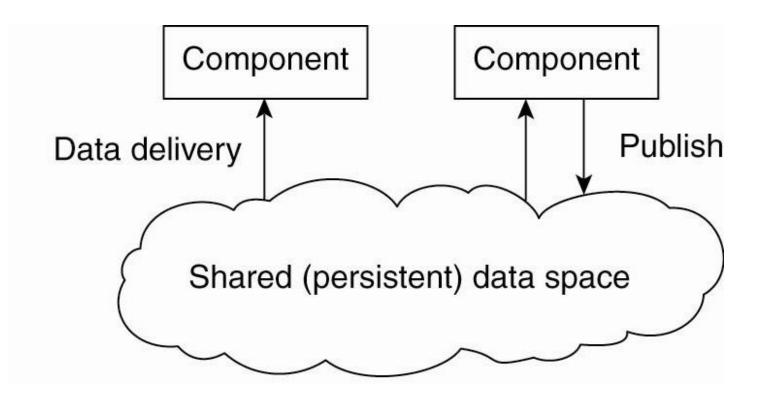
### **Event-based** architectural



asynchronous communication

• Point-to-point

### Shared data-space architectural



Combination of data-centered and event based architectures

Processes communicate asynchronously

### **Distribution Transparency**

- An important characteristic of software architectures in distributed systems is that they are designed to support distribution transparency.
- Transparency involves trade-offs
  - Performance
  - Fault tolerance
  - Ease-of-programming
- Different distributed applications require different solutions/architectures

### System Architectures for Distributed Systems

- Centralized: traditional client-server structure
  - Vertical (or hierarchical) organization of communication and control paths (as in layered software architectures)
  - Logical separation of functions into client (requesting process) and server (responder)
- Decentralized: peer-to-peer
  - Horizontal rather than hierarchical comm. and control
  - Communication paths are less structured; symmetric functionality
- **Hybrid:** combine elements of C/S and P2P
  - Edge-server systems
  - Collaborative distributed systems.
- Classification of a system as centralized or decentralized refers to communication and control organization, primarily.

### **Traditional Client-Server**

- Processes are divided into two groups (clients and servers).
- Synchronous communication: request-reply protocol
- In LANs, often implemented with a <u>connectionless</u> protocol
- In WANs, communication is typically <u>connection-oriented</u> TCP/IP
  - High likelihood of communication failures



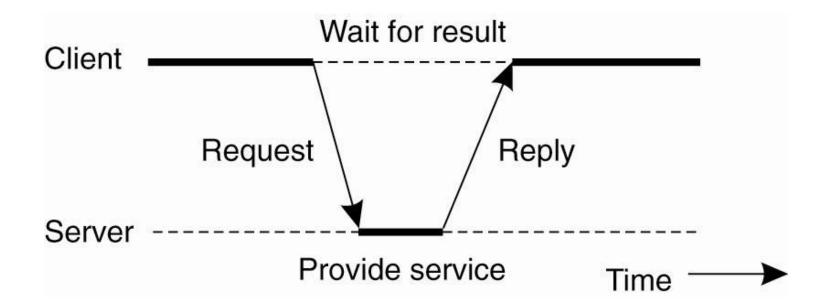


Figure 2-3. General interaction between a client and a server.

### **Transmission Failures**

- With connectionless transmissions, failure of any sort means no reply
- Possibilities:
  - Request message was lost
  - Reply message was lost
  - Server failed either before, during or after performing the service
- Can the client tell which of the above errors took place?

### Idempotency

- Typical response to lost request in connectionless communication: **re-transmission**
- Consider effect of re-sending a message such as "Increment X by 1000"
  - If first message was acted on, now the operation has been performed twice
- **Idempotent** operations: can be performed multiple times without harm
  - e.g., "Return current value of X"; check on availability of a product
  - Non-idempotent: "increment X", order a product

# Layered (software) Architecture for Client-Server Systems

- User-interface level: GUI's (usually) for interacting with end users
- **Processing level**: data processing applications the core functionality
- **Data level**: interacts with data base or file system
  - Data usually is <u>persistent;</u> exists even if no client is accessing it
  - File or database system

### Examples

- Web search engine
  - Interface: type in a keyword string
  - Processing level: processes to generate DB queries, rank replies, format response
  - Data level: database of web pages
- Stock broker's decision support system
  - Interface: likely more complex than simple search
  - Processing: programs to analyze data; rely on statistics, AI perhaps, may require large simulations
  - Data level: DB of financial information

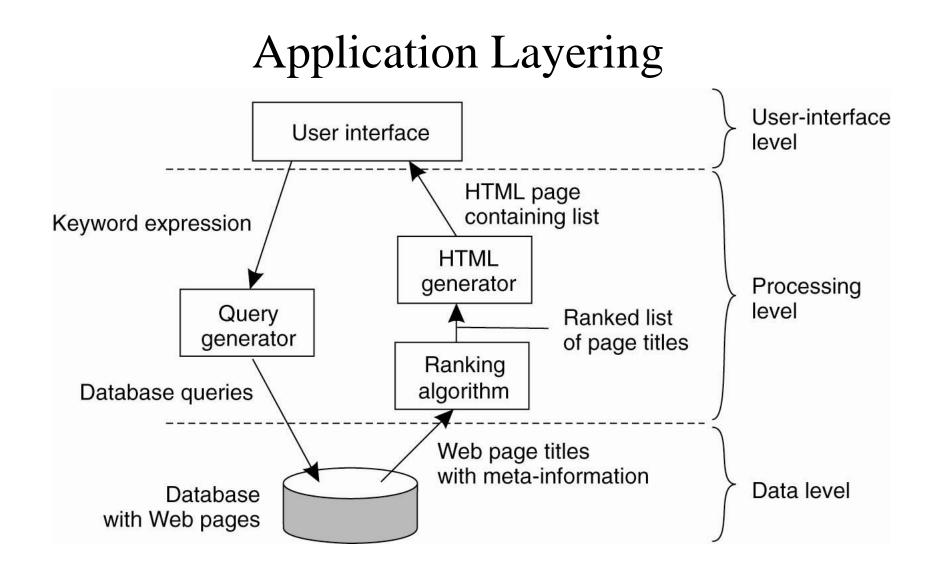


Figure 2-4. The simplified organization of an Internet search engine into three different layers.

#### Multi-tiered architectures

• *Layer* and *tier* are roughly equivalent terms, but *layer* typically implies software and *tier* is more likely to refer to hardware.

• Two-tier and three-tier are the most common

### Two-tiered C/S Architectures

- Server provides processing and data management; client provides simple graphical display (thin-client)
  - Perceived performance loss at client
  - Easier to manage, more reliable, client machines don't need to be so large and powerful
- At the other extreme, all application processing and some data resides at the client (**fat-client** approach)
  - reduces work load at server; more scalable
  - harder to manage by system admin, less secure

#### **Multitiered Architectures**

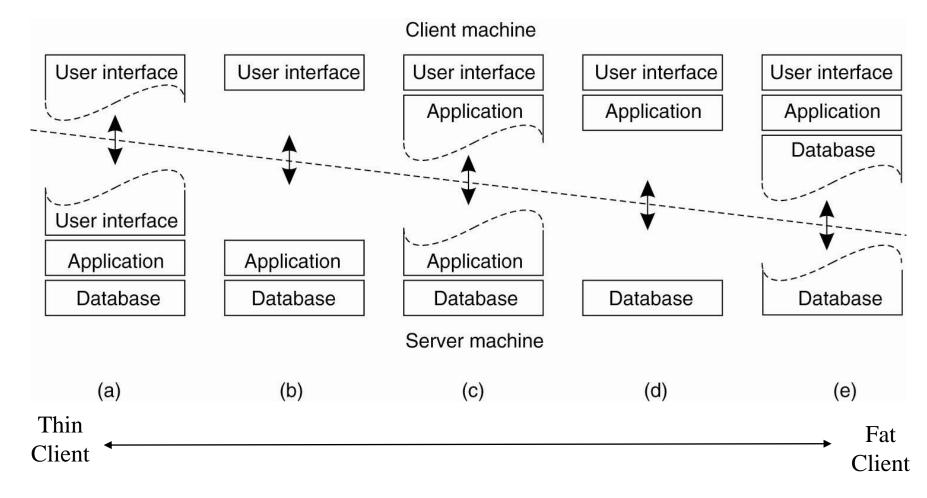


Figure 2-5. Alternative client-server organizations (a)–(e).

#### **Three-tiered Architectures**

- In some applications servers may also need to be clients, leading to a three level architecture
  - Distributed transaction processing
  - Web servers that interact with database servers
- Distribute functionality across three levels of machines instead of two.

# Multi-tiered Architectures (3 Tier Architecture)

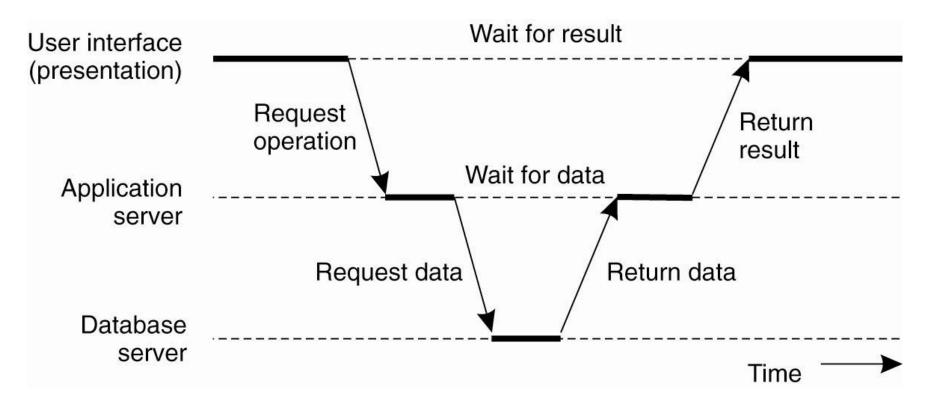


Figure 2-6. An example of a server acting as client.

# Centralized vs Decentralized Architectures

- Traditional client-server architectures exhibit vertical distribution. Each level serves a <u>different purpose</u> in the system.
  - *Logically* different components reside on different nodes
- Horizontal distribution (P2P): each node has roughly the same processing capabilities and stores/manages part of the total system data.
  - Better load balancing, more resistant to denial-of-service attacks, harder to manage than C/S
  - Communication & control is not hierarchical; all about equal

#### Peer-to-Peer

• Nodes act as both client and server; interaction is symmetric

• Each node acts as a server for part of the total system data

- Overlay networks connect nodes in the P2P system
  - Nodes in the overlay use their own addressing system for storing and retrieving data in the system
  - Nodes can route requests to locations that may not be known by the requester.

### Overlay Networks

- Are logical or *virtual* networks, built on top of a physical network
- A link between two nodes in the overlay may consist of several physical links.
- Messages in the overlay are sent to <u>logical</u> addresses, not physical (IP) addresses

• Various approaches used to resolve logical addresses to physical.

### **Overlay Networks**

• Each node in a P2P system knows how to contact several other nodes.

- The overlay network may be
  - <u>Structured</u> (nodes and content are connected according to some design that simplifies later lookups)
  - <u>Unstructured</u> (content is assigned to nodes without regard to the network topology. )

#### Structured P2P Architectures

- A common approach is to use a **distributed hash table** (DHT) to organize the nodes
- Traditional hash functions convert a key to a hash value, which can be used as an index into a hash table.
  - Keys are unique each represents an object to store in the table; e.g., at UAH, your A-number
  - The hash function value is used to insert an object in the hash table and to retrieve it.

### Structured P2P Architectures

• In a DHT, data objects and nodes are each assigned a key which hashes to a random number from a very large identifier space (to ensure uniqueness)

• A mapping function assigns objects to nodes, based on the hash function value.

• A lookup, also based on hash function value, returns the network address of the node that stores the requested object.

### Characteristics of DHT

• Scalable – to thousands, even millions of network nodes

- Search time increases more slowly than size; usually  $O(\log(N))$
- Fault tolerant able to re-organize itself when nodes fail

• Decentralized – no central coordinator

# Chord Routing Algorithm Structured P2P

- Nodes are logically arranged in a circle
- Nodes and data items have m-bit identifiers (keys) from a 2<sup>m</sup> namespace.
  - *e.g.*, a node's key is a hash of its IP address and a file's key might be the hash of its name or of its content or other unique key.
  - The hash function is *consistent*; which means that keys are distributed evenly across the nodes, with high probability.

### Inserting Items in the DHT

A data item with key value k is mapped to the node with the smallest identifier id such that id ≥ k (mod 2<sup>m</sup>)

• This node is the successor of k, or succ (k)

• Modular arithmetic is used

#### Structured Peer-to-Peer Architectures

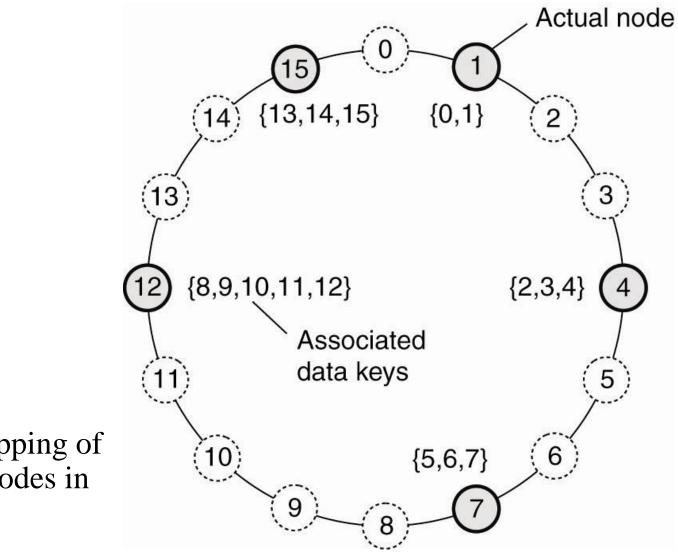


Figure 2-7. The mapping of data items onto nodes in Chord for m = 4

### Finding Items in the DHT

- Each node in the network knows the location of some fraction of other nodes.
  - If the desired key is stored at one of these nodes, ask for it directly
  - Otherwise, ask one of the nodes you know to look in *its* set of known nodes.
  - The request will propagate through the overlay network until the desired key is located
  - Lookup time is O(log(N))

# Joining & Leaving the Network

- Join
  - Generate the node's random identifier, id, using the distributed hash function
  - Use the lookup function to locate succ (id)
  - Contact succ(id) and its predecessor to insert self into ring.
  - Assume data items from succ (id)
- Leave (normally)
  - Notify predecessor & successor;
  - Shift data to succ (id)
- Leave (due to failure)
  - Periodically, nodes can run "self-healing" algorithms

# Content Addressable Networks Structured P2P

• A d-dimensional space is partitioned among all nodes

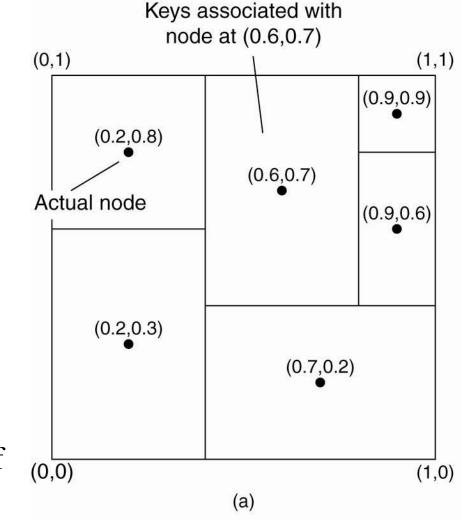
• Each node & each data item is assigned a point in the space.

• Data lookup is equivalent to knowing region boundary points and the responsible node for each region.

### Structured Peer-to-Peer Architectures

- •2-dim space [0,1] x [0,1] is divided among 6 nodes
- •Each node has an associated region
- •Every data item in CAN will be assigned a unique point in space
- •A node is responsible for all data elements mapped to its region

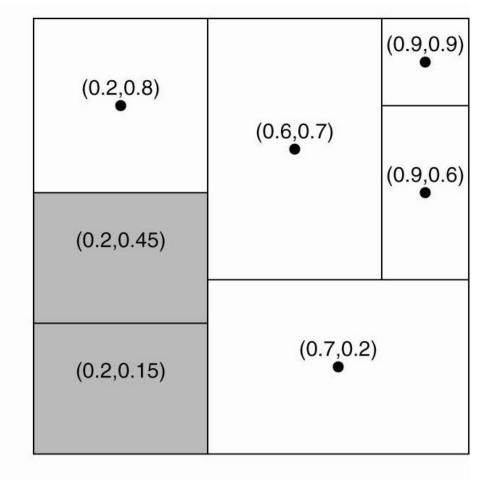
Figure 2-8. (a) The mapping of data items onto nodes in CAN
(Content Addressable Network).



### Structured Peer-to-Peer Architectures

•To add a new region, split the region

•To remove an existing region, neighbor will take over



(b)

• Figure 2-8. (b) Splitting a region when a node joins.

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# Summary

• Deterministic: If an item is in the system it will be found

• No need to know where an item is stored

• Lookup operations are relatively efficient

• DHT-based P2P systems scale well

## Unstructured P2P

- Unstructured P2P organizes the overlay network as a random graph.
- Each node knows about a subset of nodes, its "neighbors".
  - Neighbors are chosen in different ways: physically close nodes, nodes that joined at about the same time, etc. –
- Data items are randomly mapped to some node in the system & lookup is random, unlike the structured lookup in Chord.

# Locating a Data Object by Flooding

### • Send a request to all known neighbors

- If not found, neighbors forward the request to their neighbors
- Works well in small to medium sized networks, doesn't scale well
- "Time-to-live" counter can be used to control number of hops
- Example system: Freenet (Freenet uses a caching system to improve performance)

# Comparison

- Structured networks typically guarantee that if an object is in the network it will be located in a bounded amount of time – usually O(log(N))
- Unstructured networks offer no guarantees.
  - For example, some will only forward search requests a specific number of hops
  - Random graph approach means there may be loops
  - Graph may become disconnected

# Superpeers

- Maintain indexes to some or all nodes in the system
- Supports resource discovery
- Act as servers to regular peer nodes, peers to other **superpeers**
- Improve scalability by controlling floods
- Can also monitor state of network

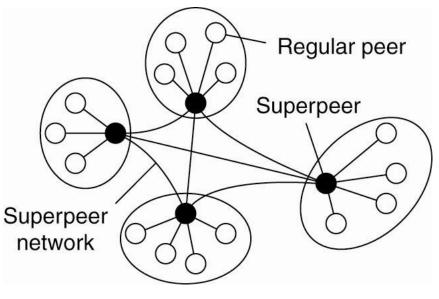


Figure 2-12.

# Hybrid Architectures

#### Combine client-server and P2P architectures

- Edge-server systems; e.g. ISPs, which act as servers to their clients, but cooperate with other edge servers to host shared content
- Collaborative distributed systems; e.g., BitTorrent, which supports parallel downloading and uploading of chunks of a file. First, interact with C/S system, then operate in decentralized manner.

### **Edge-Server Systems**

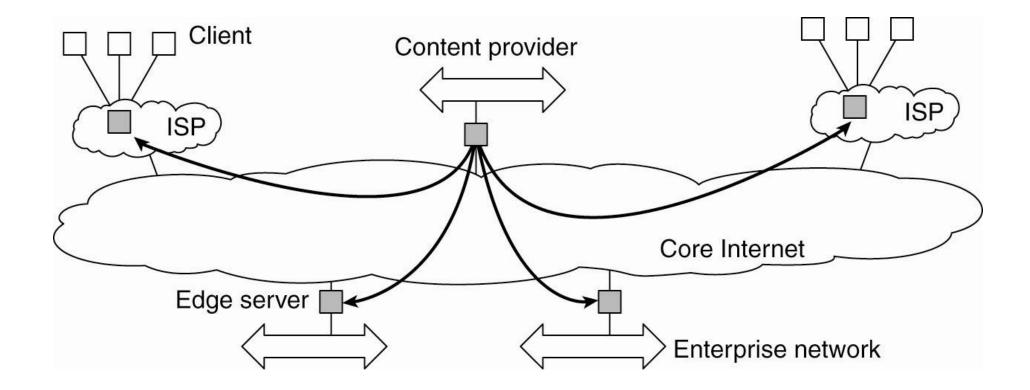


Figure 2-13. Viewing the Internet as consisting of a collection of edge servers.

# Collaborative Distributed Systems BitTorrent

- Clients contact a global directory (Web server) to locate a *.torrent* file with the information needed to locate a **tracker**
- A server that can supply a list of active nodes that have chunks of the desired file.
- Using information from the tracker, clients can download the file in chunks from multiple sites in the network.
  - Clients must also provide file chunks to other users.

# **Collaborative Distributed Systems**

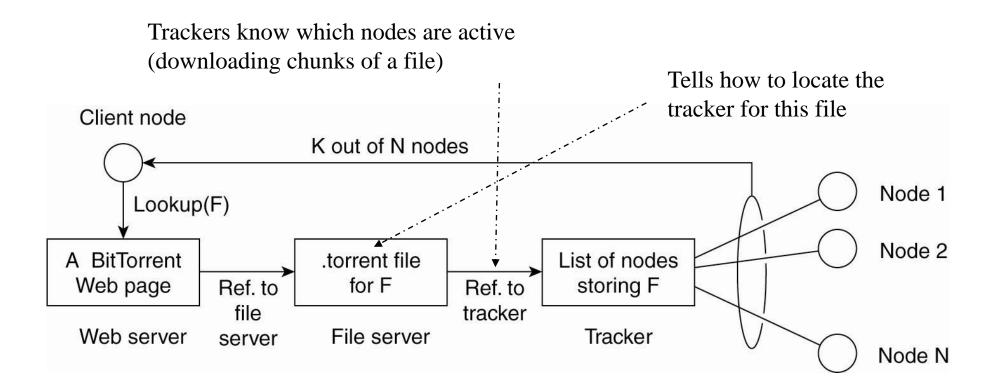


Figure 2-14. The principal working of BitTorrent [adapted with permission from Pouwelse et al. (2004)].

### **BitTorrent - Justification**

- Designed to force users of file-sharing systems to participate in sharing.
  - When a user downloads your file, he becomes in turn a server who can upload the file to other requesters.
  - Share the load doesn't swamp your server

## P2P vs Client/Server

- P2P computing allows end users to communicate without a dedicated server.
- Communication is still usually synchronous
- There is less likelihood of performance bottlenecks since communication is more distributed.
  - Data distribution leads to workload distribution.
- Resource discovery is more difficult than in centralized clientserver computing & look-up/retrieval is slower
- P2P can be more fault tolerant, more resistant to denial of service attacks because network content is distributed.
  - Individual hosts may be unreliable, but overall, the system should maintain a consistent level of service

### Architecture versus Middleware

- Where does middleware fit into an architecture?
- Middleware: the software layer between user applications and distributed platforms.
- Purpose: to provide distribution transparency
  - Applications can access programs running on remote nodes without understanding the remote environment

### Architecture versus Middleware

- Middleware may also have an architecture
  - e.g., CORBA has an object-oriented style.
- Use of a specific architectural style can make it easier to develop applications, but it may also lead to a less flexible system.

• Possible solution: develop middleware that can be customized as needed for different applications.

## Interceptors

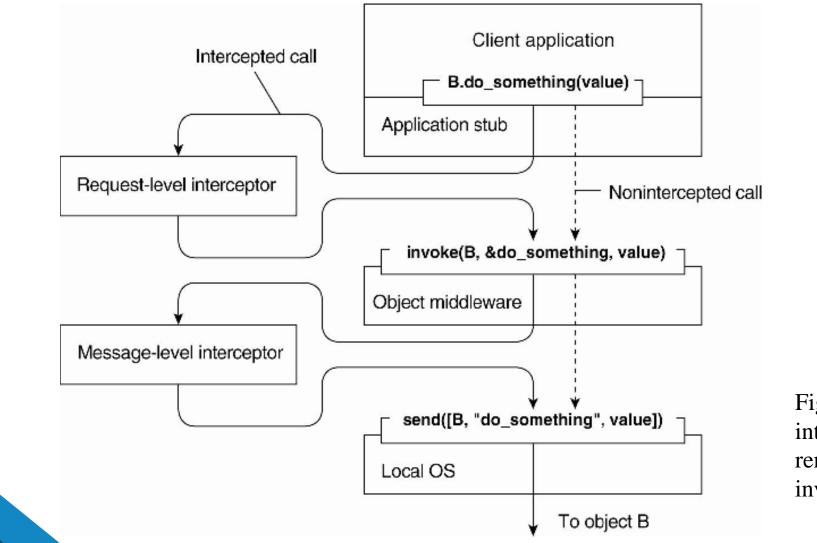


Figure 2-15. Using interceptors to handle remote-object invocations

## General Approaches to Adaptive Software

Three basic approaches to adaptive software:

- Separation of concerns
- Computational reflection
- Component-based design